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Engg. Maths Dept. Maths-II II Sem 2018-19

Department of Engg. Mathematics

Course : Engineering Mathematics-II (17MAT21).

Sem.: 2nd

Laplace Transform

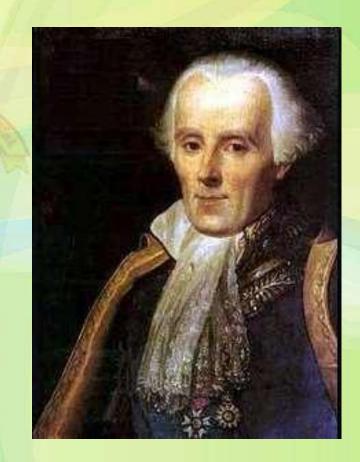
Content

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The French Newton Pierre-Simon Laplace

- Developed mathematics in astronomy, physics, and statistics
- Began work in calculus which led to the Laplace Transform
- Focused later on celestial mechanics

• One of the first scientists to suggest the existence of black holes



Why use Laplace Transforms?

- Find solution to differential equation using algebra
- Relationship to Fourier Transform allows easy way to characterize systems
- No need for convolution of input and differential equation solution
- Useful with multiple processes in system

How to use Laplace

- Find differential equations that describe system
- Obtain Laplace transform
- Perform algebra to solve for output or variable of interest
- Apply inverse transform to find solution

What are Laplace transforms?

$$F(s) = L\{f(t)\} = \int_{0}^{\infty} f(t)e^{-st}dt$$

- 1. t is real, s is complex!
- 2. Note "transform": $f(t) \rightarrow F(s)$, where t is integrated and s is variable
- 3. Conversely $F(s) \rightarrow f(t)$, t is variable and s is integrated
- 4. Assumes f(t) = 0 for all t < 0

Laplace Transform Theory

•General Theory

•Example

 $\mathcal{F}(s) = \mathcal{L}(f(t)) = \int_{0}^{\infty} e^{-st} f(t) dt = \lim_{n \to \infty} \int_{0}^{n} e^{-st} f(t) dt$

$$\begin{split} f'(t) &:: 1, \\ f'(t)) &:: \int_{0}^{\infty} e^{-ixt} 1 dt :: \lim_{x \to \infty} \begin{pmatrix} e^{-ixt} & x \\ \cdot & s & 0 \end{pmatrix} \\ &:: \lim_{x \to \infty} \begin{pmatrix} e^{-ixt} & 1 \\ \cdot & s & 0 \end{pmatrix} :: \frac{1}{s} \end{split}$$

Laplace Transform for ODEs

- Equation with initial conditions
- •Laplace transform is linear
- Apply derivative formula

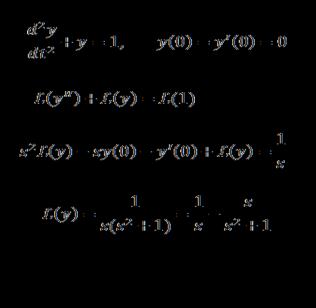


Table of selected Laplace Transforms

 $f(t) = u(t) \Leftrightarrow F(s) = \frac{1}{s}$ $f(t) = e^{-at} u(t) \Leftrightarrow F(s) = -1$ s + a $f(t) = cos(t)u(t) \Leftrightarrow F(s) = \frac{s}{s^2 + 1}$ $f(t) = sin(t)u(t) \Leftrightarrow F(s) = \frac{1}{s^2 + 1}$

More transforms

$$f(t) = t^n u(t) \Leftrightarrow F(s) = \frac{n!}{c^{n+1}}$$

$$n = 0, f(t) = u(t) \Leftrightarrow F(s) = \frac{0!}{1} = \frac{1}{1}$$
$$n = 1, f(t) = tu(t) \Leftrightarrow F(s) = \frac{s_1^{11}}{1!}$$
$$\mathfrak{P}_{20}5, f(t) = t^5 u(t) \Leftrightarrow F(s) = \frac{s^2 5!}{1!} = \frac{1}{100}$$

s⁶

c6



Note on step functions in Laplace

• Unit step function definition:

 $u(t) = 1, t \ge 0$ u(t) = 0, t < 0

 Used in conjunction with f(t) → f(t)u(t) because of Laplace integral limits:

Properties of Laplace Transforms

- Linearity
- Scaling in time
- Multiplication by tⁿ
- Integration
- Differentiation

Properties: Linearity

$L\{c_1f_1(t) + c_2f_2(t)\} = c_1F_1(s) + c_2F_2(s)$

Example :

Proof :

$$L{\sinh(t)} = y{\begin{cases} 1 e^{t} - 1 e^{-t} \\ 2 & 2 \end{cases}} = \frac{1}{2} L{e^{t}} - \frac{1}{2} L{e^{-t}} = \frac{1}{2} 2 \\ \frac{1}{2} (\frac{-1}{s-1} - \frac{1}{1s+1}) = \\\frac{1}{2} (\frac{(s+1) - (s-1)}{s^{2} - 1}) = \frac{1}{s^{2} - 1} \\ \frac{1}{2} (\frac{-1}{s^{2} - 1} - \frac{1}{s^{2} - 1}) = \frac{1}{s^{2} - 1}$$

$$L\{c_{1}f_{1}(t) + c_{2}f_{2}(t)\} =$$

$$\int_{0}^{\infty} [c_{1}f_{1}(t) + c_{2}f_{2}(t)]e^{-st}dt =$$

$$c_{1}\int_{0}^{\infty} f_{1}(t)e^{-st}dt + c_{2}\int_{0}^{\infty} f_{2}(t)e^{-st}dt =$$

$$c_{1}F_{1}(s) + c_{2}F_{2}(s)$$

Properties: Scaling in Time $L{f(at)} = {}^{1}F({}^{S})$ $\overline{a} \quad \overline{a}$

Example :

L{sin(
$$\omega$$
t)}

$$\frac{1}{\omega} \left(\frac{1}{(s_{\omega})^{2}} + 1\right) =$$

$$\frac{1}{\omega} \left(\frac{\omega^{2}}{s^{2} + \omega^{2}}\right) =$$

$$\frac{\omega}{s^{2} + \omega^{2}}$$

Proof: $L{f(at)}$ $\oint_{0}^{0} f(at)e dt =$ $\int_{0}^{0} dt = at, t = u, dt = du$ let \overline{a} \overline{a} $\int_{a}^{a} f(u) e^{-(\int_{a}^{s})u} du =$

$$\begin{array}{l} \textbf{Properties: Time Shift}\\ \textbf{L}\{f(t-t_{0})u(t-t_{0})\} = e^{-st_{0}}F(s)\\ \textbf{L}\{f(t-t_{0})u(t-10)\} = Proof:\\ e^{-10s}\\ s+a \end{array} \quad Proof:\\ e^{t-10s}\\ f(t-t_{0})u(t-t_{0})e^{-st}dt = \\ f(t-t_{0})e^{-st}dt = \\ tet \\ \begin{array}{l} \textbf{L}\{f(t-t_{0})u(t-t_{0})\} = e^{-st_{0}}F(s)\\ \textbf{L}\{f(t-t_{0})u(t-t_{0})\} = e^{-st_{0}}F(s)\\ \textbf{L}\{f(t-t_{0})u(t-t_{0})\} = e^{-st_{0}}F(s) \\ \textbf{L}\{f(t-t_{0})u(t-t_{0})e^{-st_{0}}F(s) \\ \textbf{L}\{f(t-t_{0})u(t-t_{0})e^$$

Properties: S-plane (frequency) shift

 $L\{e^{-at}f(t)\} = F(s+a)$

Proof:

Example :

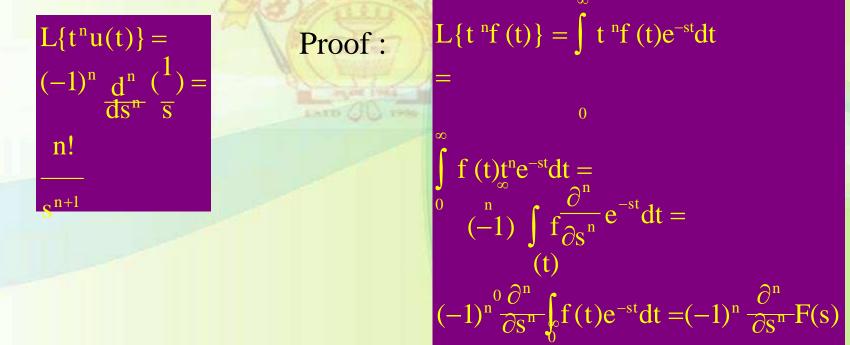
 $L\{e^{-at} \sin(\omega t)\} = \frac{1}{(s+a)^2 \Phi \omega^2}$

 $L\{e^{-at}f(t)\} =$ $\int_{0}^{\infty} e^{-at}f(t)e^{-st}dt =$ $\int_{0}^{\infty} f(t)e^{-(s+a)t}dt =$ F(s+a)

Properties: Multiplication by tⁿ

L{tⁿf(t)} = (-1)ⁿ
$$\frac{d^n}{ds^n}$$
F(s)

Example :



The "D" Operator

1. Differentiation shorthand

2. Integration shorthand

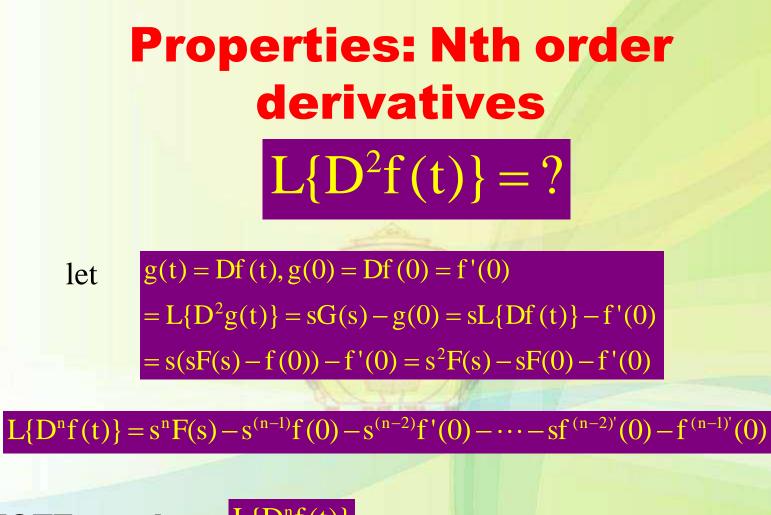


Difference in

$f(0^+), f(0^-) \& f(0)$

- The values are only different if f(t) is not continuous @ t=0
- Example of discontinuous function: u(t)

 $f(0^{-}) = \lim_{t \to 0^{-}} u(t) = 0$ $f(0^{+}) = \lim_{t \to 0^{+}} u(t) = 1$ f(0) = u(0) = 1



NOTE: to take $L{D^nf(t)}$ you need the value @ t=0 for $D^{n-1}f(t), D^{n-2}f(t), ... Df(t), f(t) \rightarrow$ called initial conditions! We will use this to solve differential equations!

Real-Life Applications

- Semiconductor mobility
- Call completion in wireless networks
- Vehicle vibrations on compressed rails
- Behavior of magnetic and electric fields above the atmosphere

